

# Datastructure

*Data Structures*

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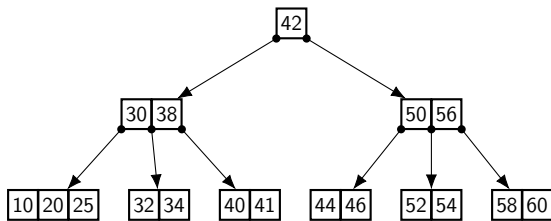
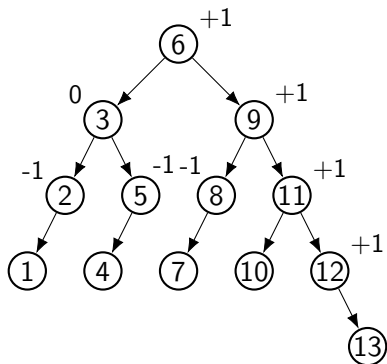
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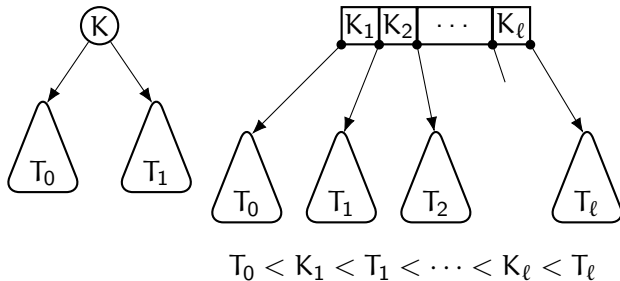
# Contents

- 6 B-Trees
  - B-Trees
  - Deleting Keys
  - Red-Black Trees

## balanced trees: AVL-tree, B-tree



## multiway search tree



# Contents

## 6 B-Trees

- B-Trees

- Deleting Keys

- Red-Black Trees

# B-tree (Bayer & McCreight, 1972)

## Definition

A *B-tree of order  $m$*  is a multi-way search tree such that

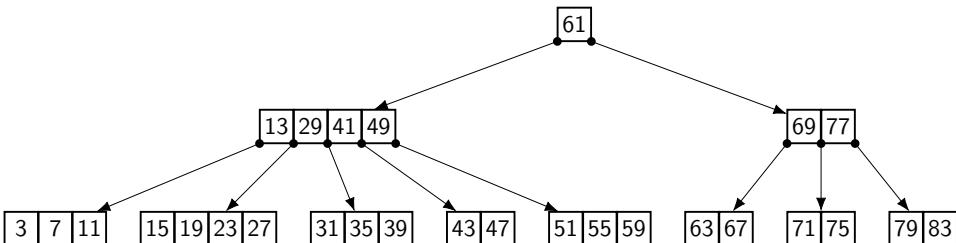
- every node has at most  $m$  children  
(contains at most  $m - 1$  keys),
- every node (other than the root) has at least  $\lceil \frac{m}{2} \rceil$  children  
(contains at least  $\lceil \frac{m}{2} \rceil - 1$  keys),
- the root contains at least one key, and
- all leaves are on the same level of the tree.

# B-tree of order 5

$$m = 5$$

$$\lceil \frac{5}{2} \rceil = 3 \leq \text{children} \leq 5$$

$$2 \leq \text{keys} \leq 4$$

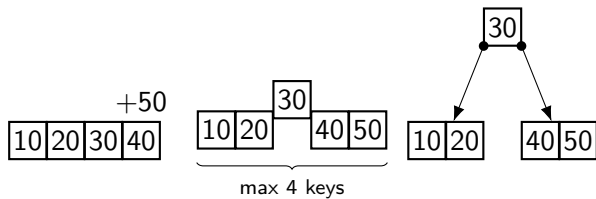




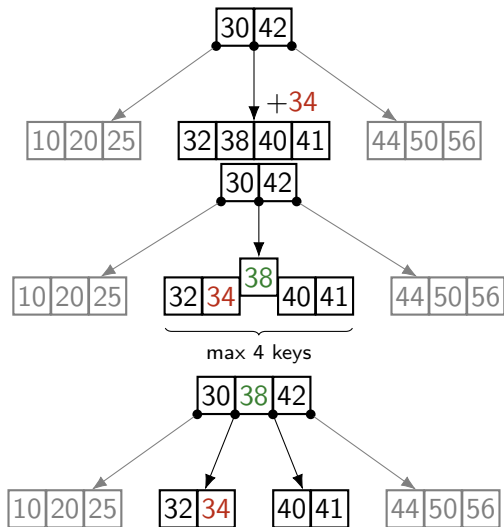
# adding keys

- Add the new key to a leaf.
- When over maximal capacity, split leaf, move middle key up.  
Recurse.
- Splits can reach the root.  
We then obtain a new root with a single key.

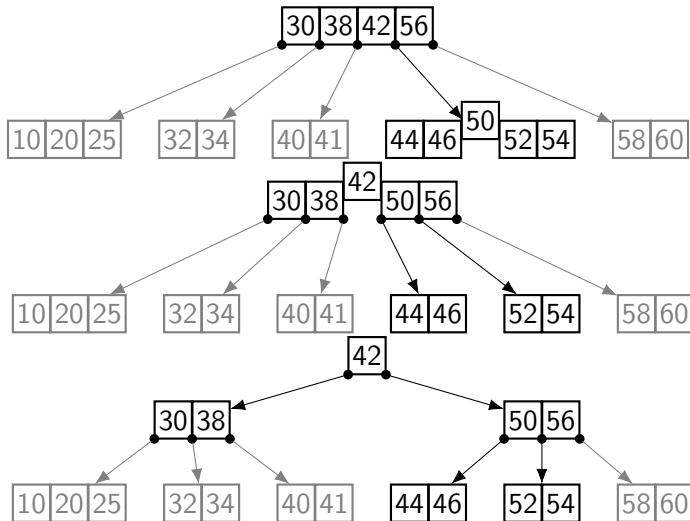
## adding keys



# adding keys



# adding keys



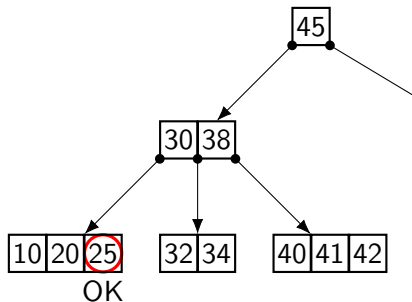
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# deleting keys

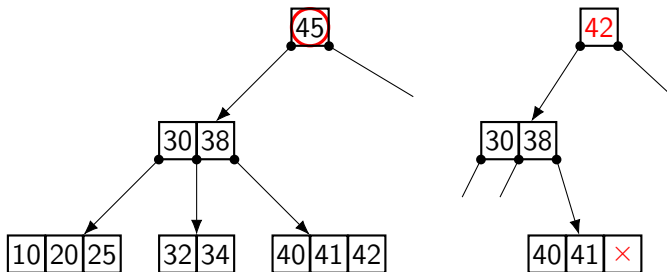
- For non-leaves: swap key with predecessor (key moves to a leaf)
- If below minimal capacity, get key from sibling with surplus, *via* parent.
- If no siblings with surplus: merge with sibling and get separating key from parent. Recurse with parent.
- Due to recursion, deletion may reach the root, and can collapse a level.

## deleting keys (order 5)



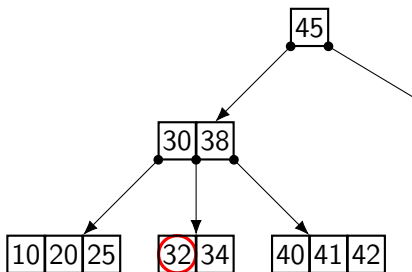
## deleting keys (order 5)

swap predecessor

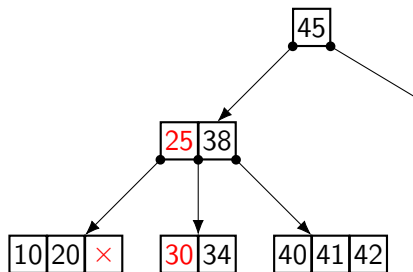




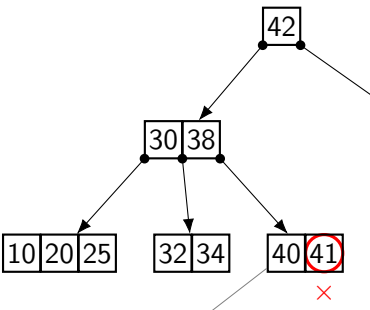
## deleting keys (order 5)



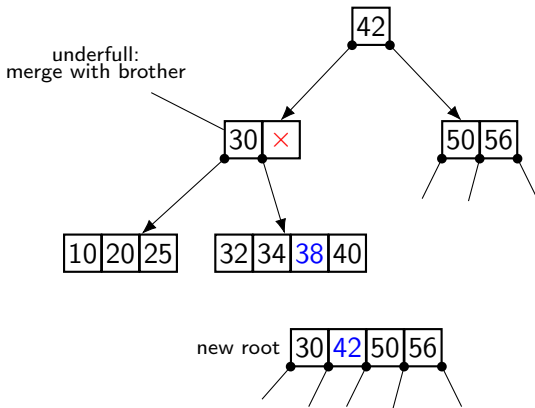
get from sibling  
(‘via’ parent)



## deleting, ctd (order 5)



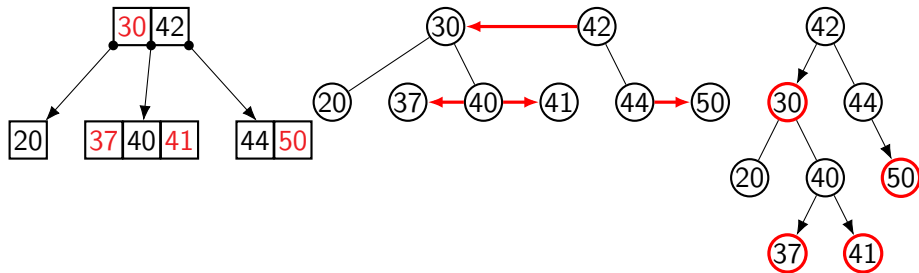
underfull:  
brother has no surplus  
merge with brother



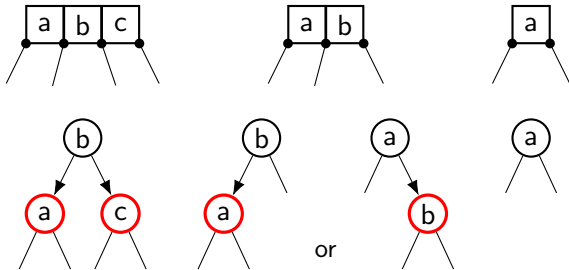
# Contents

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## 2-4-tree to red-black tree



## correspondence



## Definition

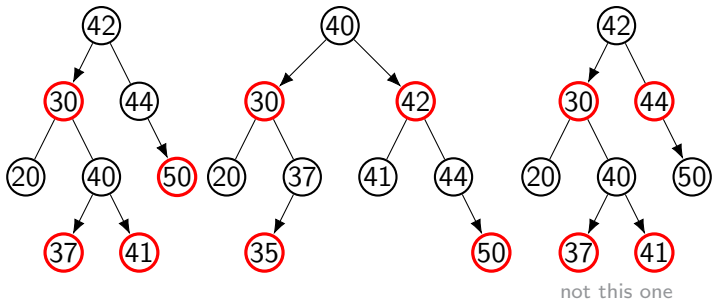
A *red-black tree* is a

- binary search tree

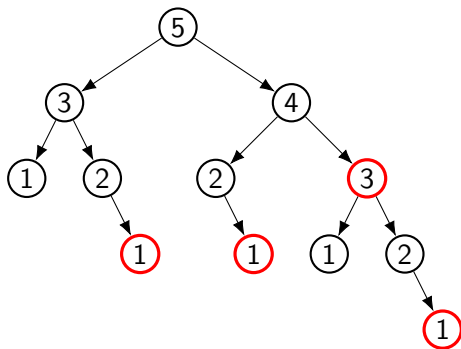
such that each node is either black or red, where

- the root is black,
- no red node is the child of another red node,
- the number of black nodes on each path from root to extended leaf (NIL-pointers) is the same.

## examples



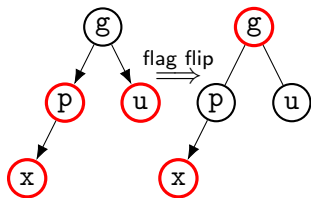
## fun fact ☒



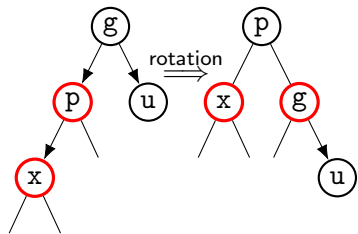
every AVL-tree can be red-black coloured



# restructuring red-red nodes



red uncle

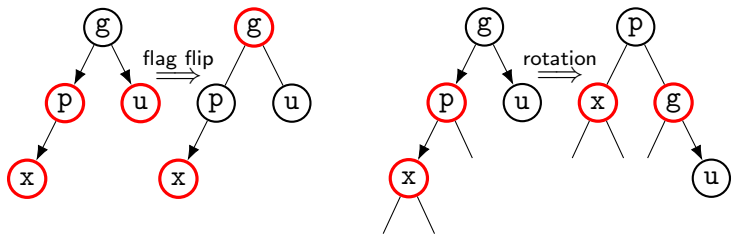


black uncle

# insertion in red-black tree

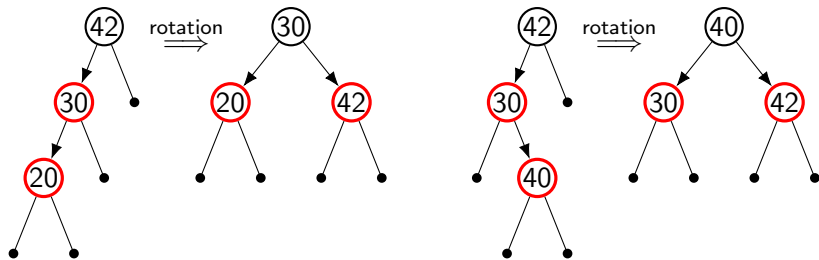
Insert as **red** leaf. problem: red node with red parent, then:

- if uncle is red: *flag-flip*. continue at grandparent.
- if uncle is black: *rotate* (see AVL-trees), repaint and stop.

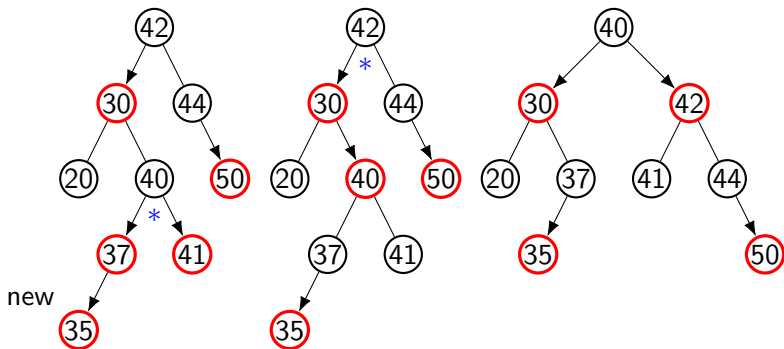


if the root has been coloured red, make it black.

# just classical single/double rotation



## adding 35



# red black trees are popular

## GNU C++ `stl_tree.h`

“Red-black tree class, designed for use in implementing STL associative containers (set, multiset, map, and multimap). The insertion and deletion algorithms are based on those in Cormen, Leiserson, and Rivest, Introduction to Algorithms (MIT Press, 1990), except that . . .”

## Linux kernel

“There are a number of red-black trees in use in the kernel. The anticipatory, deadline, and CFQ I/O schedulers all employ rbtrees to track requests; the packet CD/DVD driver does the same. The high-resolution timer code uses an rbtree to organize outstanding timer requests. The ext3 filesystem tracks directory entries in a red-black tree. Virtual memory areas (VMAs) are tracked with red-black trees, as are epoll file descriptors, cryptographic keys, and network packets in the ‘hierarchical token bucket’ scheduler.” [lwn.net/Articles/184495/](http://lwn.net/Articles/184495/)

end.